

A WATER-LEVEL GAUGE OF THE LONG-DISTANCE RECORDING TYPE.

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The figure below shows the main features of the wiring diagram. Two Selsyn induction motors A and B with wound rotors are used. The rotor of B is compelled to follow the motion of that of A. The angular position of rotor A is governed by a float mechanism operated from the water-level. An installation for recording a change of water-level of 20 ft. is described, in which one half revolution of the rotor corresponds with 2-09 feet change in water level. The error in the position of rotor B is assumed not to exceed 4 degrees with a possible error of 0.05 ft.

